

Ver 1.2

**Radiation Hardened 3.3V Quad  
Differential Line Driver**

**Datasheet**

**Part Number: B26LV31TERH**



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### Page of Revise Control

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## 1. Features

- Single 3.3V Supply
- TTL Inputs
- High Impedance Outputs when Disabled or Powered Down
- EIA RS-422 Compatible Outputs
- Full -55°C to +125°C Military Temperature Range
- Radiation-hardened design:
  - Total-dose: 100 krad(Si)
  - Latchup immune ( $LET > 75\text{MeV}\cdot\text{cm}^2/\text{mg}$ )
- Packaging options:
  - 16-lead Flatpack
- Low quiescent current

## 2. General Description

The B26LV31TERH is a quad differential line driver designed for digital data transmission over balanced lines and meets the requirements of EIA standard RS-422. Radiation hardened CMOS processing assures low power consumption, high speed, and reliable operation in the most severe radiation environments.

## 3. Function Block Diagram

B26LV31TERH function block diagram is shown in figure 3-1.

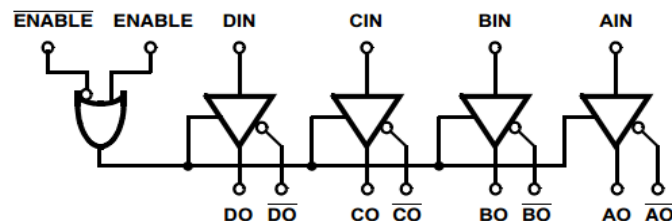


Figure 3-1 B26LV31TERH function block diagram

## 4. Packages and Pin Function Descriptions

The provided package is: FP16.

B26LV31TERH FP16 pin configuration is shown in 4-1.

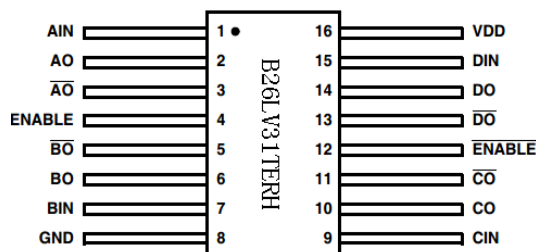


Figure 4-1 FP16 pin configuration

Table 4-1 B26LV31TERH Pin Function Descriptions

Pin No.	Name	Description
1, 7, 9, 15	AIN,BIN,CIN,DIN	Driver input pin, CMOS compatible
2, 6, 10, 14	AO,BO,CO,DO	Non-inverting driver output pin
3, 5, 11, 13	$\overline{AO}$ , $\overline{BO}$ , $\overline{CO}$ , $\overline{DO}$	Inverting driver output pin
4	ENABLE	Active high enable pin
12	$\overline{ENABLE}$	Active low enable pin
16	VDD	Power supply pin
8	GND	Ground pin

## 5. Pin List

B26LV31TERH –FP16 pin list is shown in table 5-1.

Table 5-1 B26LV31TERH –FP16 pin list

Pin No.	Symbol	Function	Pin No.	Symbol	Function
1	AIN	INPUT DATA1	9	CIN	INPUT DATA3
2	AO	OUTPUT DATA1 POSITIVE	10	CO	OUTPUT DATA3 POSITIVE

3	$\overline{AO}$	OUTPUT DATA1 NEGATIVE	11	$\overline{CO}$	OUTPUT DATA3 NEGATIVE
4	ENABLE	Active high enable pin	12	$\overline{ENABLE}$	Active low enable pin
5	$\overline{BO}$	OUTPUT DATA2 NEGATIVE	13	$\overline{DO}$	OUTPUT DATA4 NEGATIVE
6	BO	OUTPUT DATA2 POSITIVE	14	DO	OUTPUT DATA4 POSITIVE
7	BIN	INPUT DATA2	15	DIN	INPUT DATA4
8	GND	GND	16	VDD	POWER

## 6. Detailed Description

### 6.1 Function Description

The B26LV31TERH accepts TTL signal levels and converts them to RS-422 compatible outputs. This circuit uses special outputs that enable the drivers to power-down without loading down the bus. Enable and disable pins allow several devices to be connected to the same data source and addressed independently. truth table is shown in table 6-1.

Table 6-1 truth table

ENABLE	$\overline{ENABLE}$	Input	Non-inverting Output	Inverting Output
L	H	X	Z	Z
All other combinations of ENABLE inputs		L	L	H
		H	H	L

L = Low logic state

X = Irrelevant

H = High logic state

Z = TRI-STATE (high impedance)

## 6.2 Storage Condition

Packaged product should be stored in the ventilate warehouse with ambient temperature  $10^{\circ}\text{C}\sim 30^{\circ}\text{C}$  and relative humidity less than 70%. There should be no acid, alkali or other radiant gas in the environment,

## 6.3 Absolute Maximum Ratings

- a) Supply voltage range to ground potential ( $V_{DD}$ ) :  $-0.5\text{V}$  to  $7.0\text{V}$
- b) DC input voltage range ( $V_{in}$ ) :  $-0.5\text{V}$  to  $(V_{DD}+0.5\text{V})$
- c) DC output voltage ( $V_{OUT}$ ) power off :  $-0.5\text{V}$  to  $7.0\text{V}$
- d) Storage temperature ( $T_{stg}$ ) :  $-65^{\circ}\text{C}$  to  $150^{\circ}\text{C}$
- e) Lead temperature ( $T_h$ ) :  $260^{\circ}\text{C}$
- f) Junction temperature (TJ):  $150^{\circ}\text{C}$

## 6.4 Recommended Operation Conditions

- a) Supply voltage relative to ground ( $V_{DD}$ ) :  $3.0\text{V}$  to  $3.6\text{V}$
- b) Case operation temperature range(TA) :  $-55^{\circ}\text{C}$  to  $125^{\circ}\text{C}$

## 7. Specifications

All electrical characteristics are shown in table 7-1, Propagation Delay and Transition Time Waveforms are shown in Figure 7-1, Three-State Delay Waveform is shown in Figure 7-2.

Table 7-1 B26LV31TERH electrical characteristics

PARAMETER	SYMBOL	CONDITION ( $-55^{\circ}\text{C}\leq TA\leq 125^{\circ}\text{C}$ , $3.0\text{V}\leq V_{DD}\leq 3.6\text{V}$ ) unless otherwise specified	LIMIT		UNIT
			MIN	MAX	
High-level input voltage	$V_{IH}$	$V_{DD}=3.0\text{V}, 3.6\text{V}$	2.0	—	V
Low-level input voltage	$V_{IL}$	$V_{DD}=3.0\text{V}, 3.6\text{V}$	—	0.8	V
Low level input current	$I_{IL}$	$V_{IN}=0\text{V}, V_{DD}=3.6\text{V}$	-10	—	$\mu\text{A}$

PARAMETER	SYMBOL	CONDITION	LIMIT		UNIT
		(-55°C ≤ TA ≤ 125°C , 3.0V ≤ V <sub>DD</sub> ≤ 3.6V) unless otherwise specified	MIN	MAX	
High level input current	I <sub>IH</sub>	V <sub>IN</sub> = 3.6V, V <sub>DD</sub> =3.6V	—	10	μA
Differential Output Voltage	V <sub>OD1</sub>	V <sub>DD</sub> =3.0V/3.6V,R <sub>L</sub> =no load	—	4.0	V
	V <sub>OD2</sub>	V <sub>DD</sub> =3.0V/3.6V,R <sub>L</sub> =100Ω	2.0	—	V
	V <sub>OD3</sub>	V <sub>DD</sub> =3.0V/3.6V,R <sub>L</sub> =3900Ω	—	3.6	V
Difference in differential output	V <sub>OD2</sub> - $\overline{V_{OD2}}$	V <sub>DD</sub> =3.0V/3.6V,R <sub>L</sub> =100Ω	-0.4	0.4	V
Common mode output voltage	V <sub>OC</sub>	V <sub>DD</sub> =3.0V/3.6V,R <sub>L</sub> =100Ω	—	2.0	V
Difference in common mode output voltage	V <sub>OC</sub> - $\overline{V_{OC}}$	V <sub>DD</sub> =3.0V/3.6V,R <sub>L</sub> =100Ω	-0.4	0.4	V
Input clamp voltage	V <sub>CI</sub>	I <sub>IN</sub> =-18 mA, V <sub>DD</sub> =3.0V	-1.5	—	V
Output Short Circuit Current <sup>1/</sup>	I <sub>SC</sub>	V <sub>IN</sub> =V <sub>DD</sub> ,V <sub>OUT</sub> =0V and V <sub>IN</sub> =0V,V <sub>OUT</sub> =0V	-30	-160	mA
Output Three-State Current	I <sub>OZ</sub>	V <sub>DD</sub> =3.6V, ENABLE=0V , $\overline{ENABLE}$ =3.6V, V <sub>OUT</sub> =V <sub>DD</sub> or GND	-20	20	μA
Standby supply current	I <sub>CC</sub>	V <sub>DD</sub> =3.6V, V <sub>IN</sub> =V <sub>DD</sub> and GND I <sub>O</sub> =0μA	—	125	uA
Output leakage current power OFF	I <sub>off</sub>	V <sub>DD</sub> =0V, V <sub>OUT</sub> =6V,3 V	—	100	uA
		V <sub>DD</sub> =0V, V <sub>OUT</sub> =-250mV	-200	—	uA
Function test	FT	f =10MHz			
Differential Propagation Delay High to Low <sup>2/</sup>	t <sub>PHLD</sub>	V <sub>DD</sub> =3.0V R <sub>L</sub> =100Ω C <sub>L</sub> =50p Figure 7-1	5	25	ns
Differential Propagation Delay Low to High <sup>2/</sup>	t <sub>PLHD</sub>	V <sub>DD</sub> =3.0V R <sub>L</sub> =100Ω C <sub>L</sub> =50p Figure 7-1	5	25	ns



PARAMETER	SYMBOL	CONDITION	LIMIT		UNIT
		(-55°C ≤ TA ≤ 125°C , 3.0V ≤ V <sub>DD</sub> ≤ 3.6V) unless otherwise specified	MIN	MAX	
Differential skew t <sub>PHLD</sub> -t <sub>PLHD</sub> (same channel) <sup>2/</sup>	t <sub>SKD</sub>	V <sub>DD</sub> =3.0V R <sub>L</sub> =100Ω C <sub>L</sub> =50p Figure 3	—	5	ns
Pin to pin skew (same device) <sup>2/</sup>	t <sub>SK1</sub>	V <sub>DD</sub> =3.0V R <sub>L</sub> =100Ω C <sub>L</sub> =50p Figure 7-1	—	5	ns
Disable Time High to Z <sup>3/</sup>	t <sub>PHZ</sub>	V <sub>DD</sub> =3.0V R <sub>L</sub> =110Ω to GND C <sub>L</sub> =50p, Figure 7-2	—	35	ns
Disable Time Low to Z <sup>3/</sup>	t <sub>PLZ</sub>	V <sub>DD</sub> =3.0V R <sub>L</sub> =110Ω to V <sub>DD</sub> C <sub>L</sub> =50p, Figure 7-2	—	35	ns
Enable Time Z to High <sup>3/</sup>	t <sub>PZH</sub>	V <sub>DD</sub> =3.0V R <sub>L</sub> =110Ω to GND C <sub>L</sub> =50p, Figure 7-2	—	40	ns
Enable Time Z to Low <sup>3/</sup>	t <sub>PZL</sub>	V <sub>DD</sub> =3.0V R <sub>L</sub> =110Ω to V <sub>DD</sub> C <sub>L</sub> =50p, Figure 7-2	—	40	ns

1/ Only one output at a time may be shorted.

2/ Generator waveform is specified as follows: f = 1 MHz, duty cycle = 50% tr = tf ≤ 6 ns. Driver input = 0 V to 3 V with measure points equal to 1.5 V. Differential output V<sub>DIFF</sub> with measure point equal to 0 V.

3/ Generator waveform is specified as follows: f = 1 MHz, duty cycle = 50%, tr = tf ≤ 6 ns.

ENABLE/ **ENABLE** inputs 0 V to 3 V with measure points equal to 1.5 V on the inputs, to 1.3 V on the outputs for ZL and ZH, and (V<sub>OL</sub> + 0.3 V) for LZ, and (V<sub>OH</sub> - 0.3 V) for HZ.

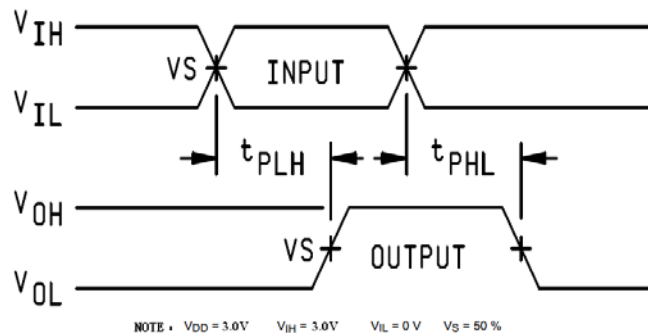


Figure.7-1. Driver Propagation Delay and Transition Time Waveforms

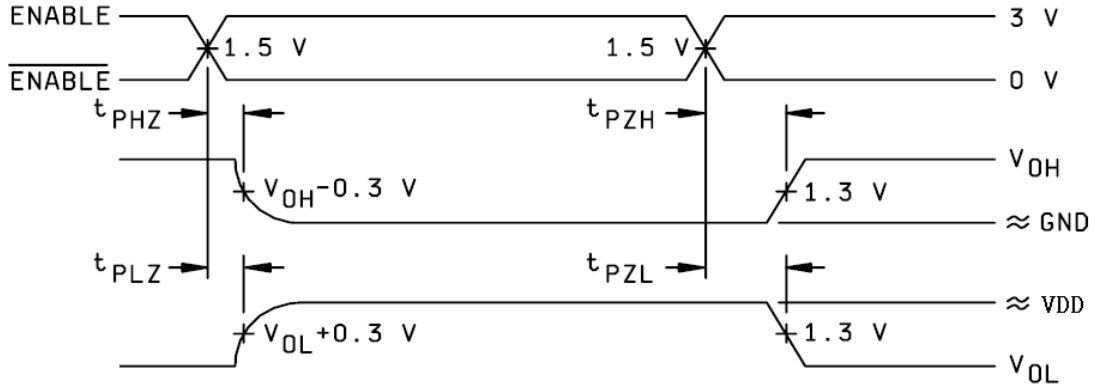


Figure.7-2. Driver Three-State Delay Waveform

## 8. Package Specifications

The specifications of FP16 package are shown in figure8-1.

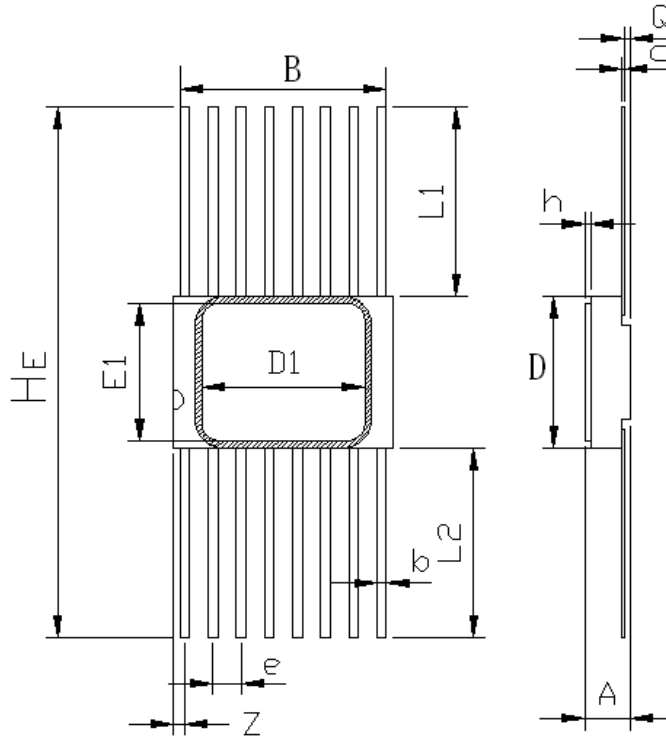


Figure 8-1 FP16 package specifications

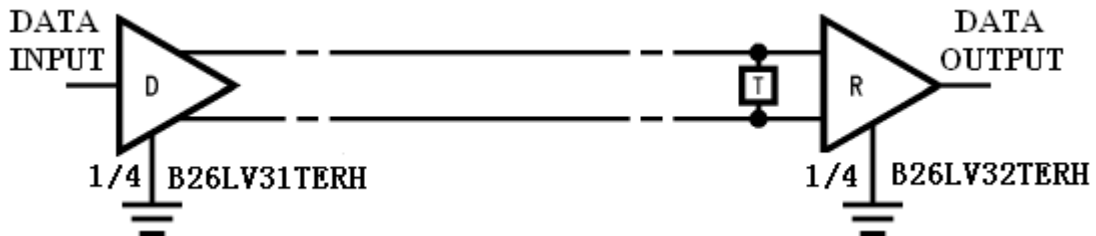
Table 8-1 size symbol list

Symbol	Value (unit: mm)		
	Min	Normal	Max

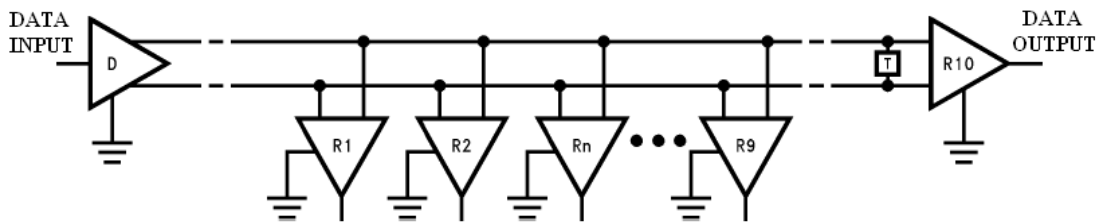
A	1.60	—	2.50
B	8.94	—	9.69
b	0.25	—	0.54
c	0.07	—	0.20
D	6.55	—	7.25
e	—	1.27	—
He	18.76	19.41	20.06
Q	0.13	—	0.90
L1	5.75	—	6.75
L2	5.75	—	6.75
Z	—	—	1.27
D1	—	7.366	—
E1	—	6.223	—
h	0.22	—	0.28

## 9. Appendix I Typical Application Example

The B26LV31TERH driver's intended use is primarily in an uncomplicated point-to-point configuration as is shown in Appendix figure.1-1. This configuration provides a clean signaling environment for quick edge rates of the drivers. The receiver is connected to the driver through a balanced media such as a standard twisted pair cable. Typically, the characteristic impedance of the media is in the range of 100Ω. A termination resistor of 100Ω should be selected to match the media and is located as close to the receiver input pins as possible. Other configurations are possible such as a multireceiver configuration, Multidrop configuration as is shown in Appendix figure.1-2.



Appendix figure.1-1. Point-to-Point Application



Appendix figure.1-2. Multidrop Application

## 10. Appendix II Replaced Product

Appendix table.1-1

Device Type	Substituted Device Type
B26LV31TERH	NSC DS26LV31QML

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